

GP1A30R

OPIC Photointerrupter with Encoder Function

■ Features

1. 2-phase (A, B) digital output
2. Possible to use plastic disk
3. High sensing accuracy
(Disk slit pitch: 0.7mm)
4. TTL compatible output
5. Compact and light

■ Applications

1. Electronic typewriters, printers
2. Robots
3. Numerical control machines

■ Absolute Maximum Ratings ($T_a = 25^\circ\text{C}$)

Parameter		Symbol	Rating	[Unit]
Input	Forward current	I _F	65	mA
	*1 Peak forward current	I _{FM}	1	A
	Reverse voltage	V _R	6	v
	power dissipation	P	100	mW
output	Supply voltage	V _{CC}	7	v
	Low level output current	I _{OL}	20	mA
	Power dissipation	P _O	250	mW
Operating temperature		T _{opr}	0 to +70	°c
Storage temperature		T _{stg}	-40 to +80	°C
*2 Soldering temperature		T _{sol}	260	°C

*1 Pulse width $\leq 100 \mu\text{s}$, Duty ratio = 0.01

*2 For 5 seconds

■ Electro-optical Characteristics

(Unless otherwise specified, $T_a = 0$ to $+70^\circ\text{C}$)

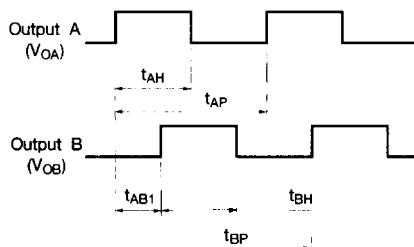
Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Input	Forward voltage	V _F	T _a = 25°C, I _F = 30mA	—	1.2	1.5	v
	Reverse current	I _R	T _a = 25°C, V _R = 3V	—	—	10	μA
output	Operating supply voltage	V _{CC}		4.5	5.0	5.5	v
	High level output voltage	V _{OH}	*3 V _{CC} = 5V, I _F = 30mA	2.4	4.9	—	v
	Low level output voltage	V _{OL}	*3 I _{OL} = 8mA, V _{CC} = 5V, I _F = 30mA	—	0.1	0.4	v
Transfer characteristics	Supply current	I _{CC}	*4 I _F = 30mA, V _{CC} = 5V	—	5	20	mA
	Duty ratio	*5 D _A	V _{CC} = 5V, I _F = 30mA,	20	50	80	%
		*5 D _B	*5 f = 2.5kHz	20	50	80	%
Response frequency		f _{MAX}	*3 V _{CC} = 5V, I _F = 30mA	—	—	5	kHz

*3 Measured under the condition shown in Measurement Conditions. *5

*4 In the condition that output A and B are low level.

$$D_A = \frac{t_{AH}}{t_{AP}} \times 100, D_B = \frac{t_{BH}}{t_{BP}} \times 100$$

■ Output Waveforms



Rotational direction Counterclockwise when seen from OPIC light detector

Fig. 1 Forward Current vs. Ambient Temperature

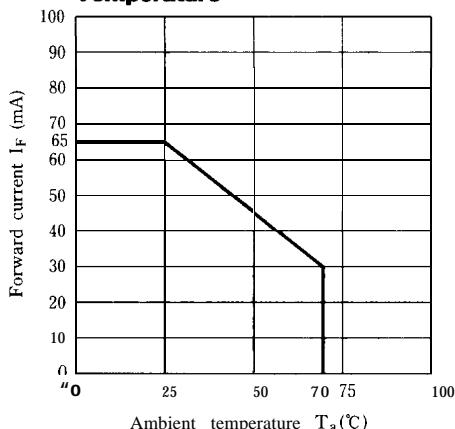


Fig. 2 Output Power Dissipation vs. Ambient Temperature

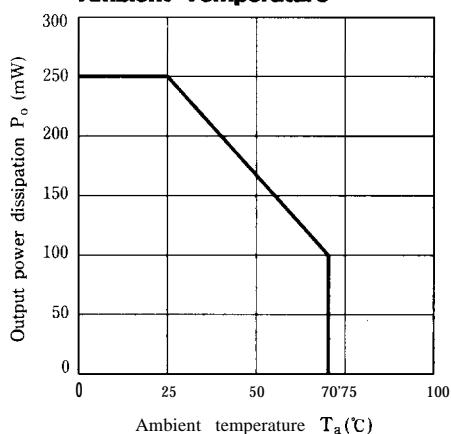


Fig. 3 Duty Ratio vs. Frequency

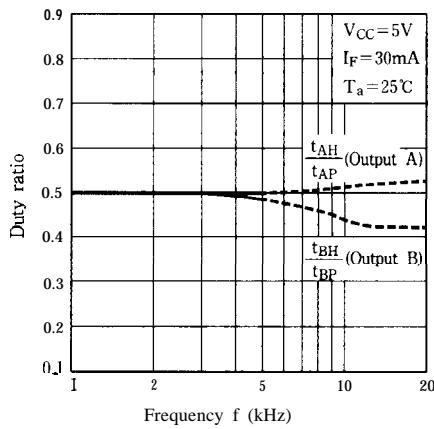


Fig. 4 Phase Difference vs. Frequency

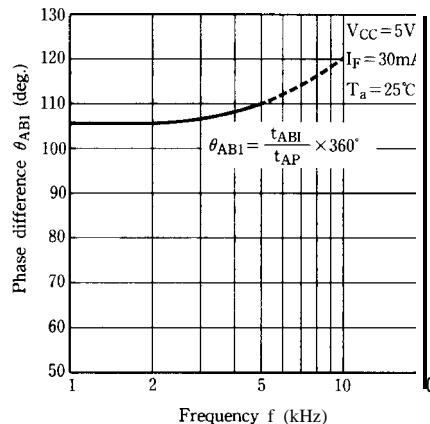


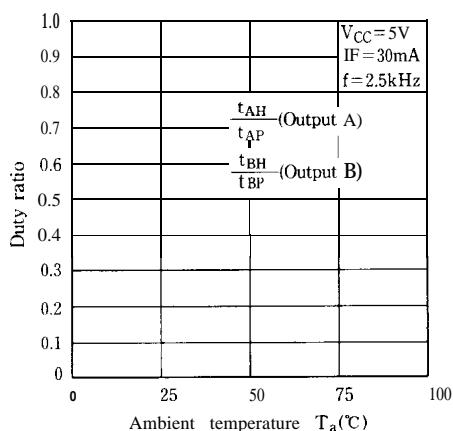
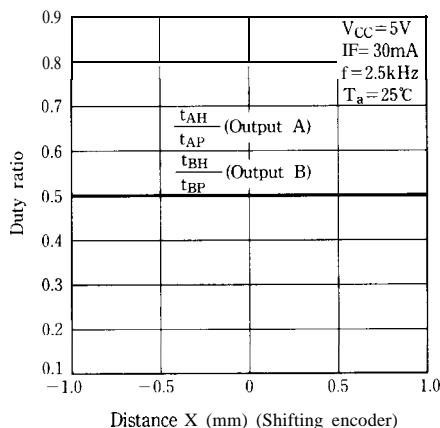
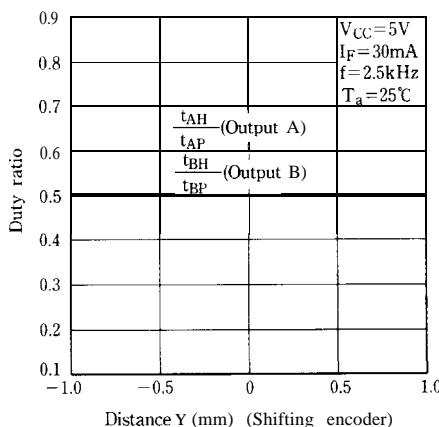
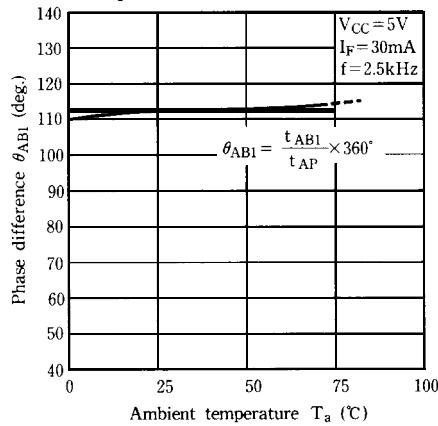
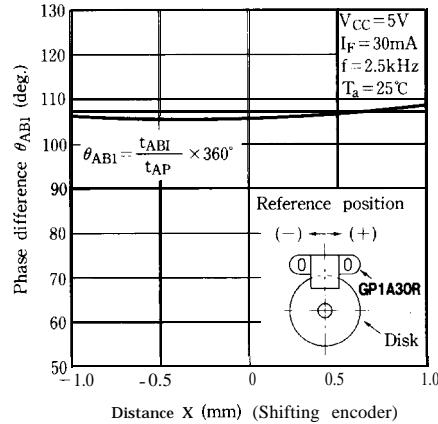
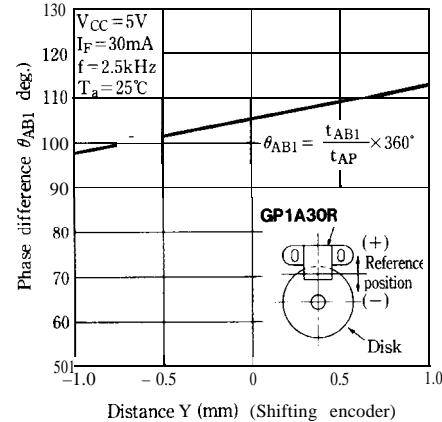
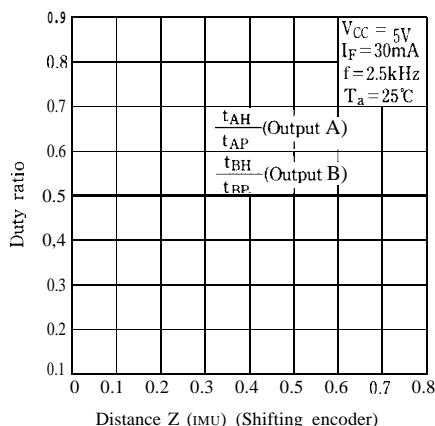
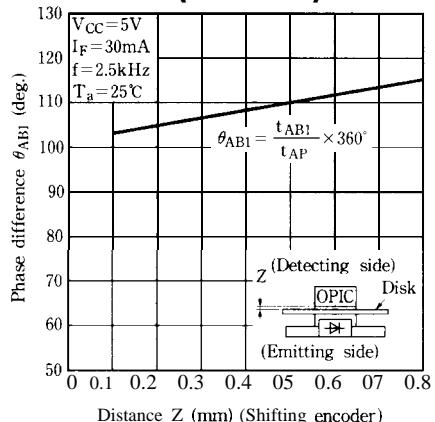
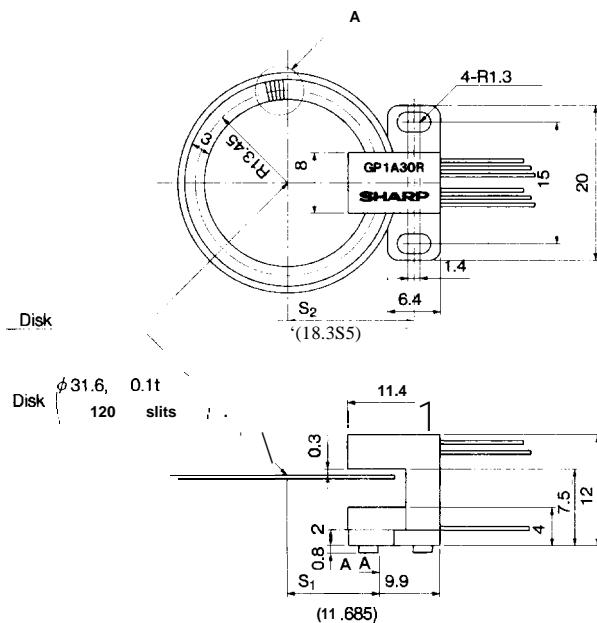
Fig. 5 Duty Ratio vs. Ambient Temperature**Fig. 7 Duty Ratio vs. Distance (X direction)****Fig. 9 Duty Ratio vs. Distance (Y direction)****Fig. 6 Phase Difference vs. Ambient Temperature****Fig. 8 Phase Difference vs. Distance (X direction)****Fig. 10 Phase Difference vs. Distance (Y direction)**

Fig.11 Duty Ratio vs. Distance (z direction)**Fig.12 Phase Difference vs. Distance (Z direction)**

■ Measurement Conditions



■ Precautions for Use

- (1) This module is designed to be operated at $I_F = 30mA$ TYP.
- (2) Fixing torque : MAX. $6kg \cdot cm$
- (3) In order to stabilize power supply line, connect a by-pass capacitor of more than $0.01 \mu F$ between V_{CC} and GND near the device.
- (4) As for other general cautions, refer to the chapter "Precautions for Use" (Page 78 to 93).

(Basic Design)

R_0 (distance between the disk center and half point of a slit), p (slit pitch), S_1 and S_2 (installing position of photointerrupter) will be provided by the following equations.

Slit pitch : P (slit center)

$$R_0 = \frac{N}{120} \times 13.45 \text{ (mm)} \quad N : \text{number of slits}$$

$$P = \frac{2 \times \pi \times R_0}{N} \text{ (mm)}$$

$$S_1 = R_0 - 1.765 \text{ (mm)}, S_2 = S_1 + 6.7 \text{ (mm)}$$

Note) When the number of slits is changed, values in parenthesis are also changed according to the number.

Enlarged drawing
of A portion
Slit pitch : P

